

Subspaces and Linear Independence

Linear Algebra - 24 DS

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Outline

- 1 Subspaces in Euclidean Spaces
- 2 Linear Independence
- 3 Practice Problems

Definition of a Subspace

Definition

A non-empty subset W of \mathbb{R}^n is called a **subspace** if it is closed under:

- 1 Vector addition:** For all $\mathbf{u}, \mathbf{v} \in W$, $\mathbf{u} + \mathbf{v} \in W$
- 2 Scalar multiplication:** For all $\mathbf{u} \in W$ and $c \in \mathbb{R}$, $c\mathbf{u} \in W$

Important Consequence of Subspace Definition

Zero Vector Requirement

Every subspace must contain the zero vector $\mathbf{0}$!

Proof.

Since W is non-empty, choose any $\mathbf{u} \in W$.

- By scalar multiplication property, for $c = 0$:
- $0 \cdot \mathbf{u} = \mathbf{0} \in W$



Quick Check

Is $W = \{(x, y) \in \mathbb{R}^2 : y = x + 1\}$ a subspace?

- Contains $(0, 1)$ but not $(0, 0)$
- Therefore, **not** a subspace!



Examples of Subspaces in \mathbb{R}^2

Lines through origin

$W = \{t\mathbf{v} : t \in \mathbb{R}\}$ for any fixed $\mathbf{v} \neq \mathbf{0}$

- x-axis: $\{(x, 0) : x \in \mathbb{R}\}$
- y-axis: $\{(0, y) : y \in \mathbb{R}\}$
- Line $y = 2x$:
 $\{(t, 2t) : t \in \mathbb{R}\}$

Trivial subspaces

- $\{\mathbf{0}\}$ - zero subspace
- \mathbb{R}^2 itself

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Trivial subspaces

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Non-examples

- Lines not through origin
- First quadrant
- Circles or curves

Examples of Subspaces in \mathbb{R}^3

Common subspaces in \mathbb{R}^3

- **Lines through origin:** $\{tv : t \in \mathbb{R}\}$
- **Planes through origin:** $\{su + tv : s, t \in \mathbb{R}\}$ for independent \mathbf{u}, \mathbf{v}

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Common subspaces in \mathbb{R}^3

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Specific examples:

- x-axis: $\{(t, 0, 0)\}$
- xy-plane: $\{(x, y, 0)\}$
- Plane $z = 0$
- Plane $x + y + z = 0$

Non-examples:

- Plane $z = 1$
- Unit sphere
- First octant

Visualizing Subspaces: Plane $x + y + z = 0$ in \mathbb{R}^3

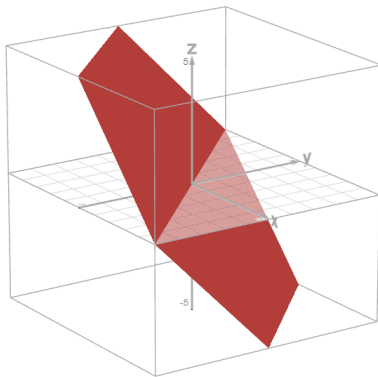


Figure: Plane $x + y + z = 0$

Visualizing Subspaces: Plane $x + y + z = 0$ in \mathbb{R}^3

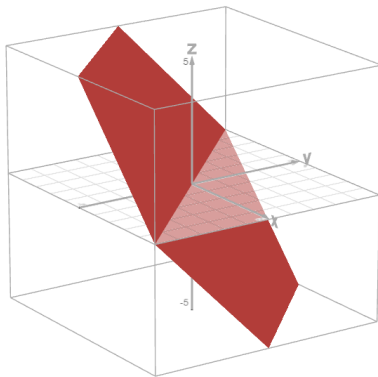
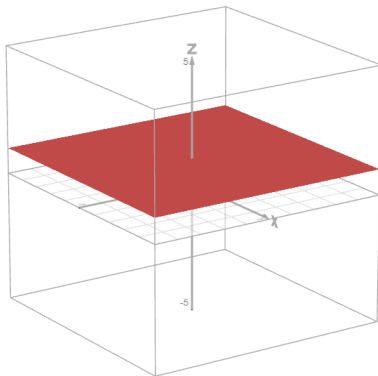


Figure: Plane $x + y + z = 0$

Visualizing Subspaces: Plane $x + y + z = 0$ in \mathbb{R}^3 Figure: Plane $z = 1$

Subspace Example 1

The xy -plane (All vectors with $z = 0$)

Set:

$$W_1 = \left\{ \begin{bmatrix} x \\ y \\ 0 \end{bmatrix} \mid x, y \in \mathbb{R} \right\} \subseteq \mathbb{R}^3$$

Check subspace conditions:

1. **Zero vector:** $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \in W_1$ (take $x = 0, y = 0$)

2. **Closed under addition:**

$$\mathbf{u} = \begin{bmatrix} x_1 \\ y_1 \\ 0 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} x_2 \\ y_2 \\ 0 \end{bmatrix} \in W_1$$

Subspace Example 2

Line through origin along vector $(1, 1, 1)$

Set:

$$W_2 = \left\{ \begin{bmatrix} t \\ t \\ t \end{bmatrix} \mid t \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\} \subseteq \mathbb{R}^3$$

Check subspace conditions:

1. **Zero vector:** $t = 0 \Rightarrow \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \in W_2$

2. **Closed under addition:**

$$\mathbf{u} = \begin{bmatrix} t_1 \\ t_1 \\ t_1 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} t_2 \\ t_2 \\ t_2 \end{bmatrix} \in W_2$$

Non-Example: What is NOT a Subspace?

The union of two lines through origin

Set:

$$W_3 = \left\{ \begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix} \mid t \in \mathbb{R} \right\} \cup \left\{ \begin{bmatrix} 0 \\ s \\ 0 \end{bmatrix} \mid s \in \mathbb{R} \right\}$$

(x-axis y-axis in the xy-plane)

Why it fails:

$$\mathbf{u} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \in W_3, \quad \mathbf{v} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \in W_3$$

$$\mathbf{u} + \mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \notin W_3$$

Definition of Linear Independence

Definition (Standard Definition)

Vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ in \mathbb{R}^n are **linearly independent** if the only solution to

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_k\mathbf{v}_k = \mathbf{0}$$

is $c_1 = c_2 = \cdots = c_k = 0$.

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Interpretation

In \mathbb{R}^2 : Two vectors are independent iff they're not collinear.

In \mathbb{R}^3 : Three vectors are independent iff they're not coplanar.



How to Check Linear Independence

[Matrix Method] To check if vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ are independent:

- 1 Form matrix A with vectors as *columns*
- 2 Find $\text{rank}(A)$ (or RREF)
- 3 If $\text{rank}(A) = k$, vectors are independent
- 4 If $\text{rank}(A) < k$, vectors are dependent

[Determinant Method for $n \times n$ matrices] For n vectors in \mathbb{R}^n :

- Form $n \times n$ matrix with vectors as columns
- Compute determinant
- $\det \neq 0 \iff$ vectors are independent

Example 1: \mathbb{R}^2 Independence Check

Example

Check if $\mathbf{v}_1 = (1, 2)$ and $\mathbf{v}_2 = (3, 4)$ are linearly independent.

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Solution:

Method 1: Form matrix and find determinant

$$A = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$$

$$\det(A) = (1)(4) - (3)(2) = 4 - 6 = -2 \neq 0$$

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Conclusion

Since $\det(A) \neq 0$, the vectors are **linearly independent**.

Example 2: \mathbb{R}^3 Independence Check

Example

Determine if $\mathbf{v}_1 = (1, 0, 1)$, $\mathbf{v}_2 = (2, 1, 3)$, $\mathbf{v}_3 = (1, 1, 2)$ are independent.

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Conclusion

$\text{rank}(A) = 2 < 3 \implies$ vectors are **linearly dependent**.

Note: $\mathbf{v}_3 = \mathbf{v}_2 - \mathbf{v}_1$

Practice Problem 1

Problem

For what value(s) of h are the vectors $\mathbf{v}_1 = (1, 2, 3)$, $\mathbf{v}_2 = (2, 4, 6)$, and $\mathbf{v}_3 = (1, h, 5)$ linearly dependent?

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Key Insight

Since \mathbf{v}_1 and \mathbf{v}_2 are already dependent, any set containing them is dependent regardless of \mathbf{v}_3 !

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Prove that if $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ is linearly independent in \mathbb{R}^3 , then $\{\mathbf{u} + \mathbf{v}, \mathbf{v} + \mathbf{w}, \mathbf{w} + \mathbf{u}\}$ is also linearly independent.

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- Since $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ independent:
$$\begin{cases} c_1 + c_3 = 0 \\ c_1 + c_2 = 0 \\ c_2 + c_3 = 0 \end{cases}$$

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Conclusion

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Find all vectors in \mathbb{R}^3 that are orthogonal to both $(1, 1, 0)$ and $(1, 0, 1)$.

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Answer

All vectors of the form $t(1, -1, -1)$ where $t \in \mathbb{R}$. This is a line through the origin (a 1-dimensional subspace).